A novel T wave cancellation method based on MAP estimation for P wave extraction¹

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Abstract. P wave and T wave in human-body electrocardiogram (ECG) signals often fuse together when atrial premature contract (APC) occurs. P waves within the fused signals are valuable for the measurement of P wave parameters as well as diagnosis of supra-ventricular arrhythmias. However, the problem of extracting P wave from the fused signals is seldom addressed. In this study, a novel T wave cancellation method for P wave extraction based on maximum a posteriori (MAP) estimation is proposed. In order to accurately cancel the T wave within the fused signal, T wave and the timing point of T wave peak are estimated simultaneously. The estimated timing point of T wave peak is used as alignment reference point for T wave subtraction. Simulation results show that the proposed method outperform the traditional T wave cancellation method in terms of both normalized mean square error and cross-correlation index. The results for real ECGs with APC demonstrate that the extracted P waves using the proposed method are more similar to the non-overlapping P waves in terms of morphology than the ones using the traditional T wave cancellation method.

Keywords: Electrocardiogram, P wave extraction, atrial premature contract, maximum a posteriori

1. Introduction

Human-body electrocardiogram (ECG) is the reflection of the heart's electrical activity, and ECG is of great value for cardiac arrhythmia diagnosis. A typical ECG signal is comprised of P wave, QRS complex and T wave. P wave is generated during atrial depolarization, while QRS complex and T wave are induced by ventricular depolarization and ventricular polarization, respectively. Compared with QRS complex, P wave is rather weak, and hence is more difficult to deal with [1]. P wave must be firstly detected (i.e., locating the onset, peak and offset points of P wave), then the related parameters, such as P wave duration, P wave amplitude and P-R interval, can be measured and the further diagnosis of supra-ventricular arrhythmias can be continued [2–5].

Unfortunately, when atrial premature contractions (APCs) occur, P wave is often fused with T wave of the preceding beat (i.e., P on T phenomenon) and becomes invisible partly or completely. In order to cal-

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culate the above mentioned parameters in this special case, P wave must be extracted from the fused signal. And extracting P wave from the fused signal is fundamental to APC analysis. It has been confirmed that APCs are strongly related with the onset of atrial fibrillation. The more frequently APC happens, the higher the risk of initiating atrial fibrillation is [6]. Due to the fusion of P wave with T wave, the P wave within the fused signal is not utilized for APC analysis. There was once a debate whether it was necessary to make measurement when P wave fuses together with T wave. CSE (Common Standards for Quantitative Electrocardiography) Working Party recommended that no measurement should be made, since the measurement is not accurate enough [7]. However, there were some opinions that it was too harsh a rule and programs should at least attempt the measurement and mark the result as unreliable.

In recent years, several works have been done to extract P wave from the fused P wave and T wave. Cabasson et al. [8–10] proposed a time delay estimation technique for P-R interval measurement during exercise or recovery, where the influence of the overlapping T wave on P-R measurement was considered. T wave was first modeled using polynomial functions or piecewise linear functions, and then maximum likelihood estimator is used to estimate P-R interval. Lin et al. [11] developed a T wave cancellation method for extracting P wave from the fused signal. The QRS-T template was subtracted from the QRS-T containing overlapping P wave, and then P wave was detected in the remaining signal. The QRS-T template in Lin's method is from the preceding normal beat.

In this paper, we focus on extracting P wave from the fused P wave and T wave in rest ECG. Considering that (1) the existing T wave cancellation methods use R wave peak as the alignment reference point before subtracting T wave, which would influence the accuracy of T wave alignment and hence would lead to strong T wave residues in the remaining signal, (2) in rest ECG, there are a lot of non-overlapping T waves and P waves (i.e., the prior information of T wave and P wave) which are not fully utilized, and (3) the performance of MAP method for extracting atrial activity (AA) signal from ECG with atrial fibrillation (AF) is satisfactory [12], we develop the MAP based method which could estimate T wave and the timing location of T wave simultaneously.

2. Modeling PDFs of P wave and T wave

In this section, we first introduce the Generalized Gaussian model. Then, the steps of modeling the PDFs of P wave and T wave are presented in detail.

2.1. A generalized gaussian model

The Generalized Gaussian model is expressed as follows [13]:

$$p(z \mid \mu, \sigma, \beta) = \frac{\omega(\beta)}{\sigma} exp\left[-c(\beta) \left|\frac{z-\mu}{\sigma}\right|^{2/(1+\beta)}\right]$$
(1)

$$c(\beta) = \left[\frac{\Gamma[1.5(1+\beta)]}{\Gamma[0.5(1+\beta)]}\right]^{1/(1+\beta)}$$
(2)

$$\omega(\beta) = \left[\frac{\Gamma[1.5(1+\beta)]^{0.5}}{(1+\beta)\Gamma[0.5(1+\beta)]^{1.5}}\right]$$
(3)

where μ and σ are the mean and standard deviation of variable z, respectively, which are estimated using the training data. Γ denotes Gamma function. β can be determined by a MAP estimation [14]:

$$\hat{\beta} = \arg \max_{\beta} \left(\Pr(z \mid \beta) \right) \tag{4}$$

where Pr(t) is the probability of variable t. The Generalized Gaussian model can describe platykurtic, Gaussian, and leptokurtic distributions by varying β . The details about the Generalized Gaussian model can refer to [13]. Through Eq.(1), the PDF of a variable can be modeled using parameters μ , σ and β .

2.2. Modeling PDFs of P wave and T wave using generalized gaussian model

In rest ECG, we can obtain non-overlapping P waves and T waves in the non-APC beats. These P waves and T waves would be used as the training samples for modeling PDFs of P wave and T wave, respectively.

In this study, both P wave and T wave are treated as vector variables. Let $X = [x_1 \cdots x_N]$ and $Y = [y_1 \cdots y_M]$ represent P wave and T wave, respectively. Let $N = N_b + N_a + 1$ and $M = M_b + M_a + 1$, where

 N_b -sample number between the onset and peak of P wave.

 N_a -sample number between the peak and offset of P wave.

 M_b -sample number between the onset and peak of T wave.

 M_a -sample number between the peak and offset of T wave.

Suppose the training beat number is K, then N_b , N_a , M_b , M_a , μ , σ and β are determined according to the following steps:

a)
$$N_b = \frac{1}{K} \sum_{k=1}^{K} N_b(k), N_a = \frac{1}{K} \sum_{k=1}^{K} N_a(k), M_b = \frac{1}{K} \sum_{k=1}^{K} M_b(k), M_a = \frac{1}{K} \sum_{k=1}^{K} M_a(k)$$
, where $N_b(k)$, $M_b = \frac{1}{K} \sum_{k=1}^{K} M_b(k)$, $M_b = \frac{1}{K} \sum$

 $N_a(k)$, $M_b(k)$ and $M_a(k)$ denote the corresponding intervals in the k-th beat.

b) Each P wave in the training beats is forced to contain $N_b + N_a + 1$ samples, namely N_b samples before P wave peak and N_a samples after P wave peak.

c) Each T wave in the training beats is forced to contain $M_b + M_a + 1$ samples, namely M_b samples before T wave peak and M_a samples after T wave peak.

d) μ and σ for P wave and T wave are estimated as:

$$\mu_X(i) = \frac{1}{K} \sum_{k=1}^K X_k(i), \quad \sigma_X(i) = \frac{1}{K-1} \sqrt{\sum_{k=1}^K (X_k(i) - \mu_X(i))^2}, \quad for \quad i = 1, \cdots, N$$
(5)

$$\mu_Y(j) = \frac{1}{K} \sum_{k=1}^K Y_k(j), \quad \sigma_Y(j) = \frac{1}{K-1} \sqrt{\sum_{k=1}^K (Y_k(j) - \mu_Y(j))^2}, \quad for \quad j = 1, \cdots, M$$
(6)

e) $\beta_X(i)i = 1, \dots, N$ and $\beta_Y(i)i = 1, \dots, M$ are computed using Eq.(4).

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After the above procedures, the PDFs of P wave vector and T wave vector can be written as Eqs.(7) and (8), respectively.

$$p_{X_{i}}(x_{i}) = \frac{\omega(\beta_{X}(i))}{\sigma_{X}(i)} exp\Big[-c(\beta_{X}(i))\Big|\frac{x_{i}-\mu_{X}(i)}{\sigma_{X}(i)}\Big|^{2/(1+\beta_{X}(i))}\Big], \quad i = 1, \cdots, N$$
(7)

$$p_{Y_j}(y_j) = \frac{\omega(\beta_Y(j))}{\sigma_Y(j)} exp\Big[-c(\beta_Y(j)) \Big| \frac{y_j - \mu_Y(j)}{\sigma_Y(j)} \Big|^{2/(1+\beta_Y(j))} \Big], \quad j = 1, \cdots, M$$
(8)

3. T wave cancellation using MAP

In traditional T wave cancellation methods, QRS-T template and QRS-T containing overlapping P wave are aligned with R wave's peak when performing subtraction. Thus, the alignment of T waves is poor, which would decrease the accuracy of T wave cancellation methods. In this section, we use MAP method to estimate T wave template and the timing point of T wave peak simultaneously, and then T wave template and T wave containing overlapping P wave can be aligned with the estimated timing point of T wave peak, which would reduce the distortion of the extracted P wave.

P wave and T wave are induced by atrial activity and ventricular activity, respectively. Moreover, the P wave and T wave within the fused signal are from different cardiac beats. In view of these, they can be assumed to be mutually independent, and thus the joint PDF of P wave vector and T wave vector is the product of their own PDFs.

From the perspective of probability theory, T wave and the timing point of T wave peak can be estimated through calculating their MAP, that is

$$[Y_{MAP}, \tilde{t}_T] = \arg\max \Pr(X, Y \mid t_P, t_T) \Pr(t_P, t_T)$$
(9)

where t_P and t_T denote the timing points of P wave peak and T wave peak, respectively. t_P and t_T are assumed to be mutually independent and obey the uniform distribution within $[t_{P-LOW}, t_{P-HIGH}]$ and $[t_{T-LOW}, t_{T-HIGH}]$, respectively. When APC happens, there are no extreme changes in R-T interval and P-R interval comparing with the normal beat. In view of this, using the training samples mentioned in section 2.2, we determine $t_{P-LOW} = t_R(i) - (T_{PR} + 30 \text{ ms}), t_{P-HIGH} = t_R(i) - (T_{PR} - 30 \text{ ms}), t_{T-LOW} = t_R(i-1) + (T_{RT} - 60 \text{ ms})$ and $t_{T-HIGH} = t_R(i-1) + (T_{RT} + 60 \text{ ms}).$

where $t_R(i)$ is the timing point of R wave in the APC beat, $t_R(i-1)$ is the timing point of R wave in the previous beat, T_{PR} and T_{RT} are the mean P-R interval (from P wave peak to R wave peak) and the mean R-T interval (from R wave peak to T wave peak) of the training beats, respectively. Considering the uniform distribution assumption of t_P and t_T , the MAP estimation can be rewritten as:

$$[Y_{MAP}, \tilde{t}_T] = \arg\max \Pr(X, Y \mid t_P, t_T) \tag{10}$$

When only single-lead ECG signal is available (e.g., in some ECG monitor systems, the log form of Eq.10 is:

$$[Y_{MAP}, \tilde{t}_T] = \arg \max_{X, Y, t_P, t_T} \log[\Pr(x_1, x_2, \cdots, x_N) \cdot \Pr(y_1, y_2, \cdots, y_M)]$$
(11)

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The specific forms of $Pr(x_1, x_2, \dots, x_N)$ and $Pr(y_1, y_2, \dots, y_M)$ depend on the overlap length and the relative location of P wave and T wave within the fused signals (see Figure 1).

Suppose the overlap length is l (l > 0); t_{Pon} and t_{Poff} represent the onset and offset timing points of P wave, respectively; t_{Ton} and t_{Toff} represent the onset and offset timing points of T wave, respectively; denotes the fused signal with L samples, from $min[t_{Pon}, t_{Ton}]$ to $max[t_{Poff}, t_{Toff}]$. Assuming the independence over time, two cases are considered:

a) When $t_{Pon} \ge t_{Ton}$ and $t_{Poff} \ge t_{Toff}$ (partially fused, see Figure 1(a)), we have:

$$Pr(x_1, x_2, \cdots, x_N) = \left(\prod_{i=1}^l p_{X_i}(x_i)\right) \cdot \left(\prod_{i=l+1}^N p_{X_i}(Z(L-N+i))\right)$$
$$Pr(y_1, y_2, \cdots, y_M) = \left(\prod_{i=1}^{M-l} p_{Y_i}(Z(i))\right) \cdot \left(\prod_{i=M-l+1}^M p_{Y_i}(Z(i) - x_{i-(M-l)})\right)$$
(12)

b) When $t_{Pon} \ge t_{Ton}$ and $t_{Poff} < t_{Toff}$ (completely fused, see Figure 1(b)), we have:

$$Pr(x_{1}, x_{2}, \cdots, x_{N}) = \prod_{i=1}^{N} p_{X_{i}i}(x_{i})$$

$$Pr(y_{1}, y_{2}, \cdots, y_{M}) = \left(\prod_{i=1}^{t_{Pon}-t_{Ton}} p_{Y_{i}i}(Z(i))\right) \cdot \left(\prod_{i=t_{Pon}-t_{Ton}+1}^{t_{Pon}-t_{Ton}+N} p_{Y_{i}i}(Z(i) - x_{i-(t_{Pon}-t_{Ton})})\right)$$

$$\cdot \left(\prod_{i=t_{Pon}-t_{Ton}+N+1}^{M} p_{Y_{i}i}(Z(i))\right)$$
(13)

When multi-lead ECG recordings are available, the log form of Eq.(10) is expressed as:

$$[Y_{MAP}, \tilde{t}_T] = \arg \max_{X, Y, t_P, t_T} LF$$
(14)

where $LF = \sum_{j=1}^{J} log[Pr(x_1^j, x_2^j, \dots, x_N^j) \cdot Pr(y_1^j, y_2^j, \dots, y_M^j)]$, *J* is the lead number, and $x_1^j, x_2^j, \dots, x_N^j$ and $y_1^j, y_2^j, \dots, y_N^j$ are the P wave vector and the T wave vector in the *j*-th lead ECG recording, respectively.



Fig. 1. Relative locations of P wave and T wave within the fused signal.

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After estimating T wave and the timing point of T wave peak, the estimated T wave is subtracted from the fused signal. Then, P wave can be detected using the traditional P wave detection procedures [15, 16]. Here, the differential threshold-based detection method [15] is adopted to detect P wave in the remaining signal.

4. Experiment results

4.1. Materials description

In this section, the proposed method (denoted as 'OURS') is compared with Lin's T wave cancellation method [11] (denoted as 'LIN'). Both the synthetic and real fused signals are used to assess these two methods.

The synthetic fused signal is generated by manually shortening TP segments of normal ECG. Ten normal ECG recordings are chosen from MIT-BIH QT database [17]. Each of these ten recordings contains two-lead ECG signals with 11 bit resolution, sampled at a frequency of 250 Hz. The fiducial points (onset, offset and peak) of P wave, T wave and QRS complex are all included in the annotation files. The first 100 beats of each normal recording are used to model the possibility distributions of P wave and T wave, and another 100 beats are used to generate the synthetic fused signals. Thus, there are totally 1000 synthetic fused beats.

Real ECG recordings with APC are chosen from MIT-BIH arrhythmia database. Here 7 recordings with APC are selected. Each recording includes two-lead ECG signals with 11 bit resolution, digitized at a sampling frequency of 360 Hz.

4.2. Performance assessment

The normalized mean square error (NMSE) and cross-correlation index (CCI) between the extracted P wave and the original P wave are used to evaluate the methods' performance for the synthetic fused signal. NMSE and CCI are defined as:

$$NMSE = \sqrt{\frac{\sum_{i=1}^{I} (S(i) - \tilde{S}(i))^2}{\sum_{i=1}^{I} (S(i))^2}}$$
(15)

$$CCI = \frac{E\left[\left(S - E(S)\right) \cdot \left(\tilde{S} - E(\tilde{S})\right)\right]}{\sigma_s \sigma_{\tilde{S}}}$$
(16)

where S and \tilde{S} are the original and the extracted P wave, respectively, I is their length. σ_s and $\sigma_{\tilde{S}}$ are standard deviations of S and \tilde{S} , respectively. The smaller the NMSE is, the more accurate the method is. CCI is used to assess the morphology similarity of two signals. Its value would be 1 in the case of completely matching and would be 0 when two signals are completely different and unrelated.

It is hard to accurately evaluate the methods' performance for real fused signals, since the true P wave is unknown. Here we calculated CCI between the extracted P wave and the P wave of the preceding beat to determine whether the extracted P wave has the similar morphology with the P waves in normal beats.

4.3. Results for synthetic fused signals

For each of the two-lead synthetic fused signals, the extracted P waves in the lead with more evident P waves are used for statistics. Table 1 summarizes NMSE and CCI at different overlapping lengths (ranging from 20 ms to 56 ms). Figures 2 and 3 are the results. The proposed method performs much better than Lin's method in terms of NMSE and CCI, especially the mean NMSE of OURS is more than 10% less than that of LIN. From the partial enlarged view shown in Figures 2(b) and 3(b), we can see that the extracted P waves by our method are much closer to the original ones.

Table 1

Overlapping length(ms)	Method	NMSE	CCI
20	OURS	0.07 ± 0.01	0.97 ± 0.06
	LIN	0.19 ± 0.25	0.93 ± 0.09
32	OURS	0.14 ± 0.28	0.93 ± 0.15
	LIN	0.29 ± 0.38	0.90 ± 0.13
44	OURS	0.27 ± 0.64	0.88 ± 0.26
	LIN	0.42 ± 0.56	0.87 ± 0.18
56	OURS	0.40 ± 0.94	0.86 ± 0.27
	LIN	0.54 ± 0.76	0.85 ± 0.18



Fig. 2. Extraction of P wave from the synthetic fused signals (overlapping length=32 ms). (a) ECG recording in the whole beat. (b) The partial enlarged view of (a).



Fig. 3. Extraction of P wave from the synthetic fused signals (overlapping length=56 ms). (a) ECG recording in the whole beat. (b) The partial enlarged view of (a).

4.4. Results for real fused signals

In MIT-BIH arrhythmia database, there are no annotation files for the locations of P waves and T waves. Thus, we first use the differential threshold-based detection method [15] to annotate the locations of the non-overlapping P waves and T waves for each real ECG recording. After this, Lin's T wave cancellation method and the proposed method are applied to extract P wave from the fused signals.

Table 2 summarizes the performance of two methods for 7 real ECG recordings with APC. On the 8th row, the average of CCIs for each method is indicated. It can be seen that, in comparison with the extracted P wave using Lin's method, the extracted P waves using the proposed method are more similar to the non-overlapping P waves in morphology. Three examples are shown in Figures 4 and 5.

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Recording name	APC number	OURS	LIN
100	33	0.77 ± 0.32	0.74 ± 0.33
108	3	0.96 ± 0.00	0.85 ± 0.06
202	30	0.54 ± 0.38	0.29 ± 0.68
213	25	0.89 ± 0.23	0.25 ± 0.77
220	73	0.83 ± 0.17	0.62 ± 0.50
223	61	0.80 ± 0.32	0.37 ± 0.67
233	6	0.80 ± 0.40	0.63 ± 0.74
Average	231	0.79 ± 0.30	0.50 ± 0.61
213 220 223 233 Average	25 73 61 6 231	$\begin{array}{c} 0.89 \pm 0.23 \\ 0.83 \pm 0.17 \\ 0.80 \pm 0.32 \\ 0.80 \pm 0.40 \\ 0.79 \pm 0.30 \end{array}$	$\begin{array}{c} 0.25 \pm 0.77 \\ 0.62 \pm 0.50 \\ 0.37 \pm 0.67 \\ 0.63 \pm 0.74 \\ 0.50 \pm 0.61 \end{array}$

Table 2 CCI for real fused signals in MIT-BIH arrhythmia database (mean \pm standard deviation)

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Fig. 4. Example 1 for extracting P wave from real fused signals.



Fig. 5. Example 2 for extracting P wave from real fused signals.

5. Conclusions

Extracting P wave from the fused signal is essential and inevitable for P wave measurement and further analysis. In this paper, we present a novel T wave cancellation method for P wave extraction based on MAP estimation. In comparison with traditional T wave cancellation methods, the proposed method has the ability to estimate T wave and the timing point of T wave peak simultaneously, which would make T wave cancellation more accurate. The experimental results confirmed the effectiveness of the proposed method, where the results for synthetic fused signals reveal that the proposed method is more accurate than the traditional T wave cancellation method.

In the experiments on real fused signals, because the true P wave within the fused signal is unknown, in this paper we just compared the extracted P waves using our method with the non-overlapping P waves. In future work, we will attempt to develop more reliable assessment indexes for the experiments on real fused signals. Moreover, we will make the further analysis for the extracted P waves in the future.

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