Muhammad I. Mustafa

Department of Mathematics, University of Sharjah, Sharjah 27272, United Arab Emirates E-mail: mmustafa@sharjah.ac.ae

Abstract. In this paper we consider a plate equation with internal feedback and viscoelastic damping localized on a part of the boundary. Without imposing restrictive assumptions on the time-dependent frictional damping, we establish an explicit and general decay rate result that allows a wider class of relaxation functions and generalizes previous results existing in the literature.

Keywords: plate equation, general decay, viscoelastic damping, relaxation function, frictional damping

1. Introduction

2.,

In this paper we are concerned with the following problem

$$u_{tt} + \Delta^2 u + \theta(t)h(u_t) = 0 \quad \text{in } \Omega \times (0, \infty), \tag{1.1}$$

$$u = \frac{\partial u}{\partial v} = 0 \quad \text{on } \Gamma_0 \times (0, \infty), \tag{1.2}$$

$$-u + \int_0^t g_1(t-s)\beta_2 u(s) \, ds = 0 \quad \text{on } \Gamma_1 \times (0,\infty), \tag{1.3}$$

$$\frac{\partial u}{\partial v} + \int_0^t g_2(t-s)\beta_1 u(s) \, ds = 0 \quad \text{on } \Gamma_1 \times (0,\infty), \tag{1.4}$$

$$u(x, y, 0) = u_0(x, y), \qquad u_t(x, y, 0) = u_1(x, y) \text{ in } \Omega,$$
(1.5)

which is a Kirchhoff plates equation with internal frictional damping and memory conditions at a part of the boundary. Here Ω is a bounded domain of \mathbb{R}^2 with a smooth boundary $\partial \Omega = \Gamma_0 \cup \Gamma_1$, $\nu = (\nu_1, \nu_2)$ is the unit outward normal to $\partial \Omega$, $\eta = (-\nu_2, \nu_1)$ is the unit tangent positively oriented on $\partial \Omega$, the integral terms in (1.3) and (1.4) are the memories responsible for the viscoelastic damping where g_1, g_2 are positive functions called the relaxation functions, θ is a time dependent coefficient of the frictional damping, and *h* is a specific function. We are denoting by β_1, β_2 the following differential operators:

$$\beta_1 u = \Delta u + (1-\mu)B_1 u, \qquad \beta_2 u = \frac{\partial \Delta u}{\partial \nu} + (1-\mu)\frac{\partial B_2 u}{\partial \eta}$$

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where

$$B_1 u = 2v_1 v_2 u_{xy} - v_1^2 u_{yy} - v_2^2 u_{xx}, \qquad B_2 u = (v_1^2 - v_2^2) u_{xy} + v_1 v_2 (u_{yy} - u_{xx})$$

and $\mu \in (0, \frac{1}{2})$ represents the Poisson coefficient. This system describes the transversal displacement u = u(x, y, t) of a thin vibrating plate subjected to internal time-dependent frictional damping and boundary viscoelastic damping.

The uniform stabilization of Kirchhoff plates with linear or nonlinear internal feedback, with $\theta \equiv 1$, was investigated by several authors. In Ammari and Tucsnak [4], Cavalcanti et al. [7], Guzman and Tucsnak [11], Komornik [18], Pazoto et al. [39], and Vasconcellos and Teixeira [41], it was proved that if *h* satisfies

$$c_1 \min\left\{|s|, |s|^q\right\} \leqslant \left|h(s)\right| \leqslant c_2 \max\left\{|s|, |s|^{\frac{1}{q}}\right\},$$

where c_1 , c_2 are positive constants, then for q = 1 the energy decay rate is exponential while for q > 1we obtain a polynomial decay rate. Similar results were also obtained for boundary frictional damping (see Horn [14], Komornik [19], Lagnese [21], Lasiecka [22], and Ji and Lasiecka [15]). Decay results for arbitrary growth of the frictional damping term have been given by Amroun and Benaissa [5] motivated by the works done by Lasiecka and Tataru [22], Liu and Zuazua [24], and Martinez [26,27] for damped wave equations. They established an explicit formula for the energy decay rates that need not to be of exponential or polynomial types. Similarly, Han and Wang [12] studied a coupled system of plate and wave equations and used internal frictional damping terms without imposing growth conditions near zero to achieve the stability and controllability of the system. In the presence of the time dependent coefficient $\theta(t)$, Mustafa [35] and Mustafa and Messaoudi [36] established for the wave equation a general energy decay result depending on both h and θ .

On the other hand, when the unique damping mechanism is given by memory conditions, we refer to Lagnese [20] and Rivera et al. [32] who considered internal viscoelastic damping and proved that the energy decays exponentially if the relaxation function g decays exponentially and polynomially if g decays polynomially. The same results were obtained by Alabau-Boussouira et al. [3] for a more general abstract equation. For boundary viscoelastic damping, if k_i is the resolvent kernel of $\frac{-g'_i}{g_i(0)}$ for i = 1, 2, Santos and Junior [40] showed that the energy decays exponentially (polynomially), provided the resolvent kernels also decay exponentially (polynomially). In Rivera et al. [33,34] investigated a class of abstract viscoelastic systems of the form

$$u_{tt}(t) + Au(t) - (g * A^{\beta}u)(t) = 0,$$
(1.6)

where A is a strictly positive, self-adjoint operator with D(A) a subset of a Hilbert space and * denotes the convolution product in the variable t. The authors showed that solutions for (1.6), when $0 < \beta < 1$, decay polynomially even if the kernel g decays exponentially. While, in the case $\beta = 1$, the solution energy decays at the same decay rate as the relaxation function.

Then, a natural question was raised: how does the energy behave as the kernel function does not necessarily decay polynomially or exponentially? Han and Wang gave an answer to the above question when treating (1.6), for $\beta = 1$, in [13]. They considered relaxation functions satisfying

$$g'(t) \leqslant -\xi(t)g(t), \quad \forall t \ge 0,$$
(1.7)

where $\xi : \mathbb{R}_+ \to \mathbb{R}_+$ is a nonincreasing differentiable function with

$$\left|\frac{\xi'(t)}{\xi(t)}\right| \leqslant k, \quad \forall t \ge 0 \tag{1.8}$$

for some constant k and showed that the rate of the decay of the energy is exactly the rate of decay of g which is not necessarily of polynomial or exponential decay type. These conditions (1.7) and (1.8) on g where first used by Messaoudi [28,29] in studying a viscoelastic wave equation. After that, Messaoudi and Mustafa [30] and Mustafa and Messaoudi [37] eliminated condition (1.8) and used only (1.7) to establish more general stability results of viscoelastic Timoshenko beams. Similarly, condition (1.7) was used by Ferreira and Messaoudi [9] to treat a nonlinear viscoelastic plate equation with a $\vec{p}(x, t)$ -Laplacian operator. We also mention the work of Alabau-Boussouira and Cannarsa [2] who considered wave equation with memory whose relaxation function is satisfying

$$g' \leqslant -\chi(g(t)),$$

where χ is a non-negative function, with $\chi(0) = \chi'(0) = 0$, and χ is strictly increasing and strictly convex on $(0, k_0]$, for some $k_0 > 0$. They also required that

$$\int_{0}^{k_{0}} \frac{dx}{\chi(x)} = +\infty, \qquad \int_{0}^{k_{0}} \frac{x \, dx}{\chi(x)} < 1, \qquad \lim_{s \to 0^{+}} \inf \frac{\chi(s)/s}{\chi'(s)} > \frac{1}{2}$$

and proved an energy decay result. In addition to these assumptions, if

$$\lim_{s \to 0^+} \sup \frac{\chi(s)/s}{\chi'(s)} < 1 \quad \text{and} \quad g' = -\chi(g(t))$$

then, in this case, an explicit rate of decay is given. Recently, the above conditions were strongly weakened by Mustafa and Messaoudi [38] and an explicit and general decay rate formula was obtained.

The interaction between viscoelastic and frictional dampings was considered by several authors. Cavalcanti and Oquendo [8] looked into wave equation of the form

$$u_{tt} - \Delta u + \int_0^t \operatorname{div} \left[a(x)g(t-s)\nabla u(s) \right] ds + b(x)h(u_t) + f(u) = 0, \quad x \in \Omega, t > 0$$

and established exponential stability for *g* decaying exponentially and *h* linear and polynomial stability for *g* decaying polynomially and *h* having a polynomial growth near zero. Using (1.7), *h* having no restrictive growth assumption near the origin, with time dependent coefficient and a(x) = b(x) = 1, Liu [25] proved a more general decay result. Similarly, Guesmia and Messaoudi [10] studied Timoshenko systems with frictional versus viscoelastic damping and Messaoudi and Mustafa [31] studied viscoelastic wave equation with boundary feedback and obtained general energy decay estimates. Once again, Kang [16,17] imposed the condition (1.7) on the relaxation functions for viscoelastic dampings in plate models which are also subject to frictional damping and they established general stability results.

Our aim in this work is to investigate (1.1)–(1.5) with both weak frictional damping and boundary viscoelastic damping. We obtain a general relation between the decay rate for the energy (when t goes to infinity) and the functions g_i , θ , and h using resolvent kernels of general-type decay and without

imposing any growth assumption near the origin on h. The result of this paper generalizes previous related results where it allows a larger class of functions g and h, from which the energy decay rates are not necessarily of exponential or polynomial types and takes into account the effect of a time dependent coefficient $\theta(t)$. The proof is based on the multiplier method and makes use of some properties of convex functions including the use of the general Young's inequality and Jensen's inequality. These convexity arguments were introduced by Lasiecka and Tataru [23] and used by Liu and Zuazua [24] and Alabau-Boussouira [1]. The paper is organized as follows. In Section 2, we present some notation and material needed for our work. Some technical lemmas and the proof of our main result will be given in Section 3.

2. Preliminaries

We use the standard Lebesgue and Sobolev spaces with their usual scalar products and norms. Throughout this paper, c is used to denote a generic positive constant. We first consider the following hypothesis

(A1). Ω is a bounded domain of \mathbb{R}^2 with a smooth boundary $\partial \Omega = \Gamma_0 \cup \Gamma_1$, where Γ_0 and Γ_1 are closed and disjoint, with meas(Γ_0) > 0, $\nu = (\nu_1, \nu_2)$ is the unit outward normal to $\partial \Omega$, $\eta = (-\nu_2, \nu_1)$ is the unit tangent positively oriented on $\partial \Omega$, and there exists a fixed point $x_0 \in \mathbb{R}^2$ such that, for $m(x) = x - x_0$, $m \cdot \nu \leq 0$ on Γ_0 and $m \cdot \nu > 0$ on Γ_1 .

Remark. Hypothesis (A1) implies that there exist constants δ_0 and R such that

 $m \cdot \nu \ge \delta_0 > 0$ on Γ_1 and $|m(x)| \le R$ for all $x \in \Omega$.

We denote by k_i the resolvent kernel of $(-g'_i/g_i(0))$ which satisfies

$$k_i(t) + \frac{1}{g_i(0)} (g'_i * k_i)(t) = -\frac{1}{g_i(0)} g'_i(t), \quad \forall i = 1, 2,$$

where * points to the convolution product

$$(u*v)(t) = \int_0^t u(t-s)v(s)\,ds.$$

By differentiating Eqs (1.3) and (1.4), we arrive at the following Volterra equations:

$$\beta_2 u + \frac{1}{g_1(0)} g'_1 * \beta_2 u = \frac{1}{g_1(0)} u_t,$$

$$\beta_1 u + \frac{1}{g_2(0)} g'_2 * \beta_1 u = -\frac{1}{g_2(0)} \frac{\partial u_t}{\partial v}$$

Using the Volterra's inverse operator and taking $\tau_i = \frac{1}{g_i(0)}$, for i = 1, 2, we get

$$\beta_2 u = \tau_1 \{ u_t + k_1 * u_t \}, \quad \text{on } \Gamma_1 \times (0, \infty),$$

$$\beta_1 u = -\tau_2 \left\{ \frac{\partial u_t}{\partial \nu} + k_2 * \frac{\partial u_t}{\partial \nu} \right\}, \quad \text{on } \Gamma_1 \times (0, \infty)$$

which gives, assuming throughout the paper that $u_0 \equiv 0$,

$$\beta_2 u = \tau_1 \{ u_t + k_1(0)u + k_1' * u \}, \quad \text{on } \Gamma_1 \times (0, \infty),$$
(2.1)

$$\beta_1 u = -\tau_2 \left\{ \frac{\partial u_t}{\partial \nu} + k_2(0) \frac{\partial u}{\partial \nu} + k_2' * \frac{\partial u}{\partial \nu} \right\}, \quad \text{on } \Gamma_1 \times (0, \infty).$$
(2.2)

Therefore, we use (2.1) and (2.2) instead of the boundary conditions (1.3) and (1.4), and also consider the following assumptions.

(A2). $k_i : \mathbb{R}_+ \to \mathbb{R}_+$, for i = 1, 2, are C^2 functions such that

$$k_i(0) > 0, \quad \lim_{t \to \infty} k_i(t) = 0, \quad k'_i(t) \le 0$$

and there exists a positive function $H \in C^1(\mathbb{R}_+)$ and H is a linear function or it is a strictly increasing and strictly convex C^2 function on (0, r], r < 1, with H(0) = H'(0) = 0, such that

$$k_i''(t) \ge H(-k_i'(t)), \quad (i = 1, 2) \ \forall t > 0.$$
 (2.3)

(A3). $h : \mathbb{R} \to \mathbb{R}$ is a nondecreasing C^0 function and there exist constants $c_1, c_2 > 0$ such that

$$c_1|s| \leq |h(s)| \leq c_2|s| \quad \text{if } |s| \geq r,$$

$$s^2 + h^2(s) \leq H^{-1}(\operatorname{sh}(s)) \quad \text{if } |s| \leq r.$$

(A4). $\theta : \mathbb{R}_+ \to \mathbb{R}_+$ is a nonincreasing C^1 function.

In the sequel we assume that system (1.1)-(1.5) has a unique solution

$$u \in L^{\infty}(\mathbb{R}_+; H^4(\Omega) \cap W) \cap W^{1,\infty}(\mathbb{R}_+; W) \cap W^{2,\infty}(\mathbb{R}_+; L^2(\Omega)),$$

where $W = \{w \in H^2(\Omega) : w = \frac{\partial w}{\partial v} = 0 \text{ on } \Gamma_0\}$. This result can be proved, for initial data in suitable function spaces, using standard arguments such as the Galerkin method (see [40]).

Let us define the bilinear form $a(\cdot, \cdot)$ as follows

$$a(u, v) = \int_{\Omega} \left\{ u_{xx} v_{xx} + u_{yy} v_{yy} + \mu (u_{xx} v_{yy} + u_{yy} v_{xx}) + 2(1 - \mu) u_{xy} v_{xy} \right\} dx \, dy \tag{2.4}$$

and, as meas $\Gamma_0 > 0$, we know that $\sqrt{a(u, u)}$ is an equivalent norm on W; that is, for some positive constants α and β ,

$$\alpha \|u\|_{H^2(\Omega)}^2 \leqslant a(u, u) \leqslant \beta \|u\|_{H^2(\Omega)}^2.$$

We state the following lemma which will be useful in what follows.

Lemma 2.1 ([21]). Let u and v be functions in $H^4(\Omega)$ and $\mu \in \mathbb{R}$. Then we have

$$\int_{\Omega} (\Delta^2 u) v \, dx = a(u, v) + \int_{\Gamma} \left\{ (\beta_2 u) v - (\beta_1 u) \frac{\partial v}{\partial v} \right\} d\Gamma$$
(2.5)

and

$$\int_{\Omega} (m \cdot \nabla v) \Delta^2 v \, dx = a(v, v) + \frac{1}{2} \int_{\Gamma} m \cdot v \Big[v_{xx}^2 + v_{yy}^2 + 2\mu v_{xx} v_{yy} + 2(1-\mu) v_{xy}^2 \Big] d\Gamma + \int_{\Gamma} \Big[(\beta_2 v) m \cdot \nabla v - (\beta_1 v) \frac{\partial}{\partial v} (m \cdot \nabla v) \Big] d\Gamma.$$
(2.6)

Now, we introduce the energy functional

$$E(t) := \frac{1}{2} \left[\int_{\Omega} |u_t|^2 dx + a(u, u) + \tau_1 \int_{\Gamma_1} \left(k_1(t) |u|^2 - \left(k_1' \circ u \right) \right) d\Gamma + \tau_2 \int_{\Gamma_1} \left(k_2(t) \left| \frac{\partial u}{\partial \nu} \right|^2 - \left(k_2' \circ \frac{\partial u}{\partial \nu} \right) \right) d\Gamma \right],$$

where

$$(f \circ w)(t) = \int_0^t f(t-s) |w(t) - w(s)|^2 ds.$$

Our main stability result is the following

Theorem 2.1. Assume that (A1)–(A4) hold. Then there exist positive constants c_1 , c_2 , c_3 and ε_0 such that the solution of (1.1)–(1.5) satisfies

$$E(t) \leqslant c_3 H_1^{-1} \left(c_1 \int_0^t \theta(s) \, ds + c_2 \right) \quad \forall t \ge 0,$$
(2.7)

where

$$H_1(t) = \int_t^1 \frac{1}{sH_0'(\varepsilon_0 s)} \, ds \quad and \quad H_0(t) = H(D(t))$$

provided that D is a positive C^1 function, with D(0) = 0, for which H_0 is a strictly increasing and strictly convex C^2 function on (0, r] and

$$\int_{0}^{+\infty} \frac{-k'_{i}(s)}{H_{0}^{-1}(k''_{i}(s))} \, ds < +\infty \quad \text{for } i = 1, 2.$$
(2.8)

Moreover, if $\int_0^1 H_1(t) dt < +\infty$ for some choice of D, then we have the improved estimate

$$E(t) \leq c_3 G^{-1} \left(c_1 \int_0^t \theta(s) \, ds + c_2 \right) \quad \text{where } G(t) = \int_t^1 \frac{1}{s H'(\varepsilon_0 s)} \, ds.$$

$$(2.9)$$

In particular, this last estimate is valid for the special case $H(t) = ct^p$, for $1 \le p < \frac{3}{2}$.

Remarks.

1. Using the properties of H, one can show that the function H_1 is strictly decreasing and convex on (0, 1], with $\lim_{t\to 0} H_1(t) = +\infty$. Therefore, Theorem 2.1 ensures

$$\lim_{t \to +\infty} E(t) = 0.$$

- 2. Hypothesis (A3) implies that sh(s) > 0, for all $s \neq 0$.
- 3. The condition (A3), with r = 1 and $\theta \equiv 1$, was introduced and employed by Lasiecka and Tataru [23] in their study of the asymptotic behavior of solutions of nonlinear wave equations with nonlinear frictional boundary damping where they obtained decay estimates that depend on the solution of an explicit nonlinear ordinary differential equation. It was also shown there that the monotonicity and continuity of *h* guarantee the existence of the function *H* with the properties stated in (A3). In our present work, we study the plate equation with both frictional damping, modulated by a time dependent coefficient $\theta(t)$, and boundary viscoelastic damping. We investigate the influence of these simultaneous damping mechanisms on the decay rate of the energy and establish an explicit and general energy decay formula, depending on the resolvent kernels k_1 and k_2 , h, and θ .
- 4. The usual exponential and polynomial decay rate estimates, already proved for $H(t) = ct^p$, $1 \le p < 3/2$, are special cases of our result. We will provide a "simpler" proof for these special cases.
- 5. The condition $k_i'' \ge d(-k_i')^p$, $1 \le p < 3/2$, assumes $(-k_i'(t)) \le \omega e^{-dt}$ when p = 1 and $(-k_i'(t)) \le \frac{\omega}{t^{\frac{1}{p-1}}}$ when 1 . Our result allows resolvent kernels whose derivatives are not necessarily of exponential or polynomial decay. For instance, if

$$k'_i(t) = -\exp(-t^q), \quad i = 1, 2$$

for 0 < q < 1, then $k_i''(t) = H(-k_i'(t))$ where, for $t \in (0, r], r < 1$,

$$H(t) = \frac{qt}{[\ln(1/t)]^{\frac{1}{q}-1}}$$

which satisfies hypothesis (A2). Also, by taking $D(t) = t^{\alpha}$, (2.8) is satisfied for any $\alpha > 1$. Therefore, if *h* satisfies (A3) with this function *H*, then we can use Theorem 2.1 and do some calculations (see [38]) to deduce that the energy decays at the rate

$$E(t) \leqslant c \exp\left(-\omega \left[\int_0^t \theta(s) \, ds\right]^q\right).$$

6. The well-known Jensen's inequality will be of essential use in establishing our main result. If *F* is a convex function on [a, b], $f : \Omega \to [a, b]$ and *j* are integrable functions on Ω , $j(x) \ge 0$, and $\int_{\Omega} j(x) dx = C > 0$, then Jensen's inequality states that

$$F\left[\frac{1}{C}\int_{\Omega}f(x)j(x)\,dx\right] \leqslant \frac{1}{C}\int_{\Omega}F\left[f(x)\right]j(x)\,dx.$$

7. Since $\lim_{t \to +\infty} k_i(t) = 0$ and $(-k'_i(t))$ is nonnegative and nonincreasing, then we can easily deduce that $\lim_{t \to +\infty} (-k'_i(t)) = 0$. Similarly, assuming the existence of the limit, we find that $\lim_{t \to +\infty} k''_i(t) = 0$. Hence, there is $t_1 > 0$ large enough such that $k'_i(t_1) < 0$ and

$$\max\{k_i(t), -k'_i(t), k''_i(t)\} < \min\{r, H(r), H_0(r)\}, \quad (i = 1, 2) \ \forall t \ge t_1.$$
(2.10)

As k'_i is nondecreasing, $k'_i(0) < 0$ and $k'_i(t_1) < 0$, then $k'_i(t) < 0$ for any $t \in [0, t_1]$ and

$$0 < -k'_i(t_1) \leqslant -k'_i(t) \leqslant -k'_i(0), \quad (i = 1, 2) \ \forall t \in [0, t_1].$$

Therefore, since H is a positive continuous function, then

$$a \leq H(-k'_i(t)) \leq b, \quad (i = 1, 2) \ \forall t \in [0, t_1]$$

for some positive constants *a* and *b*. Consequently, for all $t \in [0, t_1]$,

$$k_i''(t) \ge H\left(-k_i'(t)\right) \ge a = \frac{a}{k_i'(0)}k_i'(0) \ge \frac{a}{k_i'(0)}k_i'(t) \quad (i = 1, 2)$$

which gives, for some positive constant d,

$$k_i''(t) \ge -dk_i'(t), \quad (i = 1, 2) \ \forall t \in [0, t_1].$$
 (2.11)

8. If different functions H_1 , H_2 , and H_3 have the properties mentioned in (A2) and (A3) such that $k_1''(t) \ge H_1(-k_1'(t)), k_2''(t) \ge H_2(-k_2'(t))$, and $s^2 + h^2(s) \le H_3^{-1}(\operatorname{sh}(s))$, then there is $r < \min\{r_1, r_2, r_3\}$ small enough so that, say, $H_1(t) \le \min\{H_2(t), H_3(t)\}$ on the interval (0, r]. Thus, the function $H(t) = H_1(t)$ satisfies both (A2) and (A3), $\forall t \ge t_1$.

3. Proof of the main result

In this section we prove Theorem 2.1. For this purpose, we establish several lemmas.

Lemma 3.1. Under the assumptions (A1)–(A4), the energy functional satisfies, along the solution of (1.1), the estimate

$$E'(t) = -\theta(t) \int_{\Omega} u_t h(u_t) dx - \frac{\tau_1}{2} \int_{\Gamma_1} \left(2|u_t|^2 - k_1'(t)|u|^2 + k_1'' \circ u \right) d\Gamma$$
$$- \frac{\tau_2}{2} \int_{\Gamma_1} \left(2\left| \frac{\partial u_t}{\partial \nu} \right|^2 - k_2'(t) \left| \frac{\partial u}{\partial \nu} \right|^2 + k_2'' \circ \frac{\partial u}{\partial \nu} \right) d\Gamma$$
$$\leqslant 0.$$
(3.1)

Proof. Multiplying the equation (1.1) by u_t , integrating by parts over Ω , and using (2.5) and the boundary conditions (2.1) and (2.2), we get

$$\frac{1}{2} \frac{d}{dt} \left\{ \int_{\Omega} |u_t|^2 dx + a(u, u) \right\}$$

$$= -\int_{\Gamma_1} (\beta_2 u) u_t d\Gamma + \int_{\Gamma_1} (\beta_1 u) \frac{\partial u_t}{\partial \nu} d\Gamma - \theta(t) \int_{\Omega} u_t h(u_t) dx$$

$$= -\tau_1 \int_{\Gamma_1} u_t^2 - \frac{k_1(0)\tau_1}{2} \frac{d}{dt} \int_{\Gamma_1} u^2 - \tau_1 \int_{\Gamma_1} \{k_1' * u\} u_t d\Gamma - \tau_2 \int_{\Gamma_1} \left| \frac{\partial u_t}{\partial \nu} \right|^2$$

$$- \frac{k_2(0)\tau_2}{2} \frac{d}{dt} \int_{\Gamma_1} \left| \frac{\partial u}{\partial \nu} \right|^2 - \tau_2 \int_{\Gamma_1} \{k_2' * \frac{\partial u}{\partial \nu}\} \frac{\partial u_t}{\partial \nu} d\Gamma - \theta(t) \int_{\Omega} u_t h(u_t) dx.$$

Then, making use of the identity

$$(f * w)w_t = -\frac{1}{2}f(t)|w(t)|^2 + \frac{1}{2}f' \circ w - \frac{1}{2}\frac{d}{dt}\left[f \circ w - \left(\int_0^t f(s)\,ds\right)|w|^2\right],$$

our conclusion follows. \Box

Now we are going to construct a Lyapunov functional \mathcal{L} equivalent to E, with which we can show the desired result.

Lemma 3.2. Under the assumptions (A1)–(A4), the functional

$$\psi(t) := \int_{\Omega} (m \cdot \nabla u) u_t \, dx$$

satisfies, along the solution, the estimate

$$\frac{d}{dt}\psi(t) \leq \frac{1}{2}\int_{\Gamma_{1}} m \cdot \nu |u_{t}|^{2} d\Gamma - \int_{\Omega} |u_{t}|^{2} dx - \left(1 - \frac{\epsilon c}{2}\right)a(u, u)
+ \frac{2\tau_{1}^{2}}{\epsilon}\int_{\Gamma_{1}} \left[|u_{t}|^{2} + k_{1}^{2}(t)|u|^{2} - k_{1}(0)\left(k_{1}' \circ u\right)\right]d\Gamma + \frac{c}{2\epsilon}\int_{\Omega}h^{2}(u_{t}) dx
+ \frac{2\tau_{2}^{2}}{\epsilon}\int_{\Gamma_{1}} \left[\left|\frac{\partial u_{t}}{\partial \nu}\right|^{2} + k_{2}^{2}(t)\left|\frac{\partial u}{\partial \nu}\right|^{2} - k_{2}(0)\left(k_{2}' \circ \frac{\partial u}{\partial \nu}\right)\right]d\Gamma
- \left(\frac{1}{2} - \frac{\epsilon c}{2}\right)\int_{\Gamma_{1}} m \cdot \nu \left[u_{xx}^{2} + u_{yy}^{2} + 2\mu u_{xx}u_{yy} + 2(1 - \mu)u_{xy}^{2}\right]d\Gamma.$$
(3.2)

Proof. Direct computations, taking v = u in (2.6), we get

$$\frac{d}{dt}\psi(t) = \int_{\Omega} (m \cdot \nabla u_t) u_t \, dx + \int_{\Omega} (m \cdot \nabla u) u_{tt} \, dx$$

$$= \frac{1}{2} \int_{\Gamma_1} m \cdot v |u_t|^2 d\Gamma - \int_{\Omega} |u_t|^2 dx - \theta(t) \int_{\Omega} (m \cdot \nabla u) h(u_t) dx$$
$$- a(u, u) - \int_{\Gamma} \left[(\beta_2 u)(m \cdot \nabla u) - (\beta_1 u) \frac{\partial}{\partial v}(m \cdot \nabla u) \right] d\Gamma$$
$$- \frac{1}{2} \int_{\Gamma} m \cdot v \left[u_{xx}^2 + u_{yy}^2 + 2\mu u_{xx} u_{yy} + 2(1 - \mu) u_{xy}^2 \right] d\Gamma.$$
(3.3)

Let us examine the integrals over Γ_0 in (3.3). Since $u = \frac{\partial u}{\partial v} = 0$ on Γ_0 , we have $B_1 u = B_2 u = 0$ on Γ_0 and

$$\frac{\partial}{\partial \nu}(m \cdot \nabla u) = (m \cdot \nu)\Delta u,$$

$$u_{xx}^2 + u_{yy}^2 + 2\mu u_{xx} u_{yy} + 2(1-\mu)u_{xy}^2 = (\Delta u)^2 \quad \text{on } \Gamma_0$$

since

$$u_{xx}u_{yy} - (u_{xy})^2 = 0 \quad \text{on } \Gamma_0.$$

Therefore, from (3.3), we have

$$\frac{d}{dt}\psi(t) = \frac{1}{2}\int_{\Gamma_1} m \cdot \nu |u_t|^2 d\Gamma - \int_{\Omega} |u_t|^2 dx - \theta(t) \int_{\Omega} (m \cdot \nabla u)h(u_t) dx$$
$$- a(u, u) + \frac{1}{2}\int_{\Gamma_0} m \cdot \nu (\Delta u)^2 d\Gamma$$
$$- \frac{1}{2}\int_{\Gamma_1} m \cdot \nu [u_{xx}^2 + u_{yy}^2 + 2\mu u_{xx}u_{yy} + 2(1-\mu)u_{xy}^2] d\Gamma$$
$$- \int_{\Gamma_1} (\beta_2 u)(m \cdot \nabla u) d\Gamma + \int_{\Gamma_1} (\beta_1 u) \frac{\partial}{\partial \nu} (m \cdot \nabla u) d\Gamma.$$
(3.4)

Using the Young inequality, we have

$$\left| \int_{\Gamma_1} (\beta_2 u) (m \cdot \nabla u) \, d\Gamma \right| \leq \frac{1}{2\epsilon} \int_{\Gamma_1} |\beta_2 u|^2 \, d\Gamma + \frac{\epsilon}{2} \int_{\Gamma_1} |m \cdot \nabla u|^2 \, d\Gamma, \tag{3.5}$$

$$\left|\int_{\Gamma_1} (\beta_1 u) \frac{\partial}{\partial \upsilon} (m \cdot \nabla u) \, d\Gamma\right| \leq \frac{1}{2\epsilon} \int_{\Gamma_1} |\beta_1 u|^2 \, d\Gamma + \frac{\epsilon}{2} \int_{\Gamma_1} \left|\frac{\partial}{\partial \upsilon} (m \cdot \nabla u)\right|^2 \, d\Gamma, \tag{3.6}$$

$$-\theta(t)\int_{\Omega}(m\cdot\nabla u)h(u_t)\,dx \leqslant \frac{c}{2\epsilon}\int_{\Omega}h^2(u_t)\,dx + \frac{\epsilon}{2}\int_{\Omega}|m\cdot\nabla u|^2\,dx,\tag{3.7}$$

where ϵ is a positive constant. Using the trace theory, we obtain

$$\int_{\Gamma_1} |m \cdot \nabla u|^2 \, d\Gamma + \int_{\Gamma_1} \left| \frac{\partial}{\partial \nu} (m \cdot \nabla u) \right|^2 \, d\Gamma + \int_{\Omega} |m \cdot \nabla u|^2 \, dx$$

$$\leq ca(u, u) + c \int_{\Gamma_1} m \cdot v \left[u_{xx}^2 + u_{yy}^2 + 2\mu u_{xx} u_{yy} + 2(1-\mu) u_{xy}^2 \right] d\Gamma.$$
(3.8)

Substituting the inequalities (3.5)–(3.8) into (3.4) and taking into account the fact that $m \cdot \nu \leq 0$ on Γ_0 , we have

$$\begin{aligned} \frac{d}{dt}\psi(t) &\leq \frac{1}{2}\int_{\Gamma_1} m \cdot \nu |u_t|^2 d\Gamma - \int_{\Omega} |u_t|^2 dx - \left(1 - \frac{\epsilon c}{2}\right) a(u, u) \\ &+ \frac{1}{2\epsilon}\int_{\Gamma_1} |\beta_1 u|^2 d\Gamma + \frac{1}{2\epsilon}\int_{\Gamma_1} |\beta_2 u|^2 d\Gamma + \frac{c}{2\epsilon}\int_{\Omega} h^2(u_t) dx \\ &- \left(\frac{1}{2} - \frac{\epsilon c}{2}\right)\int_{\Gamma_1} m \cdot \nu \left[u_{xx}^2 + u_{yy}^2 + 2\mu u_{xx}u_{yy} + 2(1 - \mu)u_{xy}^2\right] d\Gamma. \end{aligned}$$

Since, by Hölder inequality,

$$(k'_1 * u)(t) = -\int_0^t k'_1(t-s)(u(t) - u(s)) ds + k_1(t)u(t) - k_1(0)u(t) \leq \left[-\int_0^t k'_1(s) ds \right]^{\frac{1}{2}} [(k'_1 \circ u)(t)]^{\frac{1}{2}} + k_1(t)u(t) - k_1(0)u(t) \leq \left[-k_1(0)(k'_1 \circ u)(t) \right]^{\frac{1}{2}} + k_1(t)u(t) - k_1(0)u(t)$$

then

$$\beta_2 u \leq \tau_1 \{ u_t + k_1(t)u + [-k_1(0)(k'_1 \circ u)(t)]^{\frac{1}{2}} \},$$

similarly

$$\beta_1 u \leqslant -\tau_2 \bigg\{ \frac{\partial u_t}{\partial \nu} + k_2(t) \frac{\partial u}{\partial \nu} + \bigg[-k_2(0) \bigg(k_2' \circ \frac{\partial u}{\partial \nu} \bigg)(t) \bigg]^{\frac{1}{2}} \bigg\}.$$

Consequently, our conclusion easily follows. \Box

Proof of Theorem 2.1. For N > 0, we define

$$\mathcal{L}(t) := NE(t) + \psi(t).$$

Combining (3.1) and (3.2) and using the facts that $k'_i < 0, k''_i > 0$ and $|m \cdot v| \leq R$, we obtain

$$\mathcal{L}'(t) \leq -\left(\tau_1 N - \frac{R}{2} - \frac{2\tau_1^2}{\epsilon}\right) \int_{\Gamma_1} |u_t|^2 d\Gamma - \left(\tau_2 N - \frac{2\tau_2^2}{\epsilon}\right) \int_{\Gamma_1} \left|\frac{\partial u_t}{\partial \nu}\right|^2 d\Gamma - \left(1 - \frac{\epsilon c}{2}\right) a(u, u) + \frac{2\tau_1^2}{\epsilon} \int_{\Gamma_1} k_1^2(t) |u|^2 d\Gamma + \frac{2\tau_2^2}{\epsilon} \int_{\Gamma_1} k_2^2(t) \left|\frac{\partial u}{\partial \nu}\right|^2 d\Gamma$$

$$-\int_{\Omega} |u_{t}|^{2} dx - \frac{2\tau_{1}^{2}k_{1}(0)}{\epsilon} \int_{\Gamma_{1}} k_{1}' \circ u \, d\Gamma - \frac{2\tau_{2}^{2}k_{2}(0)}{\epsilon} \int_{\Gamma_{1}} k_{2}' \circ \frac{\partial u}{\partial \nu} \, d\Gamma$$
$$-\left(\frac{1}{2} - \frac{\epsilon c}{2}\right) \int_{\Gamma_{1}} m \cdot \nu \left[u_{xx}^{2} + u_{yy}^{2} + 2\mu u_{xx} u_{yy} + 2(1-\mu)u_{xy}^{2}\right] d\Gamma$$
$$+ \frac{c}{2\epsilon} \int_{\Omega} h^{2}(u_{t}) \, dx.$$
(3.9)

Then choosing $0 < \epsilon < \frac{1}{c}$, and N large enough so that

$$\tau_1 N - \frac{R}{2} - \frac{2\tau_1^2}{\epsilon} > 0, \qquad \tau_2 N - \frac{2\tau_2^2}{\epsilon} > 0,$$

so, we arrive at

$$\mathcal{L}'(t) \leqslant -\int_{\Omega} |u_t|^2 dx - \frac{1}{2}a(u, u) + c \int_{\Omega} h^2(u_t) dx + \frac{2\iota_1^2}{\epsilon} \int_{\Gamma_1} k_1^2(t) |u|^2 d\Gamma + \frac{2\iota_2^2}{\epsilon} \int_{\Gamma_1} k_2^2(t) \left|\frac{\partial u}{\partial \nu}\right|^2 d\Gamma - c \int_{\Gamma_1} k_1' \circ u \, d\Gamma - c \int_{\Gamma_1} k_2' \circ \frac{\partial u}{\partial \nu} d\Gamma,$$

which, using Trace theory and the fact that $\lim_{t\to\infty} k_i(t) = 0$, for i = 1, 2, yields, for large t_1 ,

$$\mathcal{L}'(t) \leqslant -mE(t) - c \int_{\Gamma_1} k_1' \circ u \, d\Gamma - c \int_{\Gamma_1} k_2' \circ \frac{\partial u}{\partial \nu} \, d\Gamma + c \int_{\Omega} h^2(u_t) \, dx, \quad \forall t \ge t_1.$$
(3.10)

On the other hand, we can choose N even larger (if needed) so that

$$\mathcal{L}(t) \sim E(t), \tag{3.11}$$

which means that, for some constants $\alpha_1, \alpha_2 > 0$,

$$\alpha_1 E(t) \leq \mathcal{L}(t) \leq \alpha_2 E(t).$$

Now, we consider the following partition of Ω

$$\Omega_1 = \{ x \in \Omega : |u_t| \leq r \}, \qquad \Omega_2 = \{ x \in \Omega : |u_t| > r \}$$

and use (A3), (A4), (2.11), and (3.1) to conclude that, for any $t \ge t_1$,

$$-\theta(t)\int_{0}^{t_{1}}k_{1}'(s)\int_{\Gamma_{1}}\left|u(t)-u(t-s)\right|^{2}d\Gamma\,ds+c\theta(t)\int_{\Omega_{2}}h^{2}(u_{t})\,dx$$

$$\leqslant\frac{c}{d}\int_{0}^{t_{1}}k_{1}''(s)\int_{\Gamma_{1}}\left|u(t)-u(t-s)\right|^{2}d\Gamma\,ds+c\theta(t)\int_{\Omega_{2}}u_{t}h(u_{t})\,dx$$

$$\leqslant-cE'(t),$$
(3.12)

$$-\theta(t)\int_{0}^{t_{1}}k_{2}'(s)\int_{\Gamma_{1}}\left|\frac{\partial u(t)}{\partial \nu}-\frac{\partial u(t-s)}{\partial \nu}\right|^{2}d\Gamma ds$$

$$\leqslant \frac{c}{d}\int_{0}^{t_{1}}k_{2}''(s)\int_{\Gamma_{1}}\left|\frac{\partial u(t)}{\partial \nu}-\frac{\partial u(t-s)}{\partial \nu}\right|^{2}\leqslant -cE'(t).$$
(3.13)

Next, we take $F(t) = \theta(t)\mathcal{L}(t) + 2cE(t)$, which is clearly equivalent to E(t) as θ is nonincreasing, and use (3.10) and (3.12)–(3.13), to get, for all $t \ge t_1$,

$$F'(t) \leq -m\theta E(t) - c\theta \int_{t_1}^t k_1'(s) \int_{\Gamma_1} \left| u(t) - u(t-s) \right|^2 d\Gamma \, ds$$
$$- c\theta \int_{t_1}^t k_2'(s) \int_{\Gamma_1} \left| \frac{\partial u(t)}{\partial \nu} - \frac{\partial u(t-s)}{\partial \nu} \right|^2 d\Gamma \, ds + c\theta \int_{\Omega_1} h^2(u_t) \, dx. \tag{3.14}$$

(I) $H(t) = ct^p$ and $1 \le p < \frac{3}{2}$: This means, using Holder's inequality, that

$$c\theta \int_{\Omega_1} h^2(u_t) \, dx \leq c\theta \int_{\Omega_1} \left[u_t h(u_t) \right]^{\frac{1}{p}} \, dx \leq c\theta \left[\int_{\Omega_1} u_t h(u_t) \, dx \right]^{\frac{1}{p}}$$
$$\leq c\theta^{\frac{p-1}{p}} \left[-E'(t) \right]^{\frac{1}{p}}.$$

• Case 1. p = 1: Estimate (3.14) yields

$$F'(t) \leq -m\theta(t)E(t) + c\theta(t) \int_{\Gamma_1} (k_1'' \circ u)(t) d\Gamma + c\theta(t) \int_{\Gamma_1} k_2'' \circ \frac{\partial u}{\partial v} - cE'(t)$$
$$\leq -m\theta(t)E(t) - cE'(t), \quad \forall t \geq t_1,$$

which gives

$$(F+cE)'(t) \leqslant -m\theta(t)E(t), \quad \forall t \ge t_1.$$

Hence, using the fact that $F + cE \sim E$, we easily obtain

$$E(t) \leqslant c' e^{-c \int_0^t \theta(s) \, ds} = c' G^{-1} \left(c \int_0^t \theta(s) \, ds \right).$$

• Case 2. $1 : One can easily show that <math>\int_0^{+\infty} [-k'_i(s)]^{1-\delta_0} ds < +\infty$ for any $\delta_0 < 2 - p$ and i = 1, 2. Using this fact (3.1), and the trace theory and choosing t_1 even larger if needed, we deduce that, for all $t \ge t_1$,

$$\eta(t) := \int_{t_1}^t \left[-k_1'(s) \right]^{1-\delta_0} \int_{\Gamma_1} \left| u(t) - u(t-s) \right|^2 d\Gamma \, ds$$

$$\leqslant 2 \int_{t_1}^t \left[-k_1'(s) \right]^{1-\delta_0} \int_{\Gamma_1} \left(\left| u(t) \right|^2 + \left| u(t-s) \right|^2 \right) d\Gamma \, ds$$

$$\leqslant cE(0) \int_{t_1}^t \left[-k_1'(s) \right]^{1-\delta_0} ds < 1$$
(3.15)

and

$$\gamma(t) := \int_{t_1}^t \left[-k_2'(s) \right]^{1-\delta_0} \int_{\Gamma_1} \left| \frac{\partial u(t)}{\partial \nu} - \frac{\partial u(t-s)}{\partial \nu} \right|^2 d\Gamma \, ds$$

$$\leqslant 2 \int_{t_1}^t \left[-k_2'(s) \right]^{1-\delta_0} \int_{\Gamma_1} \left| \frac{\partial u(t)}{\partial \nu} \right|^2 + \left| \frac{\partial u(t-s)}{\partial \nu} \right|^2 d\Gamma \, ds$$

$$\leqslant c E(0) \int_{t_1}^t \left[-k_2'(s) \right]^{1-\delta_0} \, ds < 1.$$
(3.16)

Then, Jensen's inequality (3.1), hypothesis (A2), and (3.15) lead to

$$\begin{split} &-\int_{t_1}^t k_1'(s) \int_{\Gamma_1} |u(t) - u(t-s)|^2 d\Gamma ds \\ &= \int_{t_1}^t \left[-k_1'(s) \right]^{\delta_0} \left[-k_1'(s) \right]^{1-\delta_0} \int_{\Gamma_1} |u(t) - u(t-s)|^2 d\Gamma ds \\ &= \int_{t_1}^t \left[-k_1'(s) \right]^{(p-1+\delta_0)(\frac{\delta_0}{p-1+\delta_0})} \left[-k_1'(s) \right]^{1-\delta_0} \int_{\Gamma_1} |u(t) - u(t-s)|^2 d\Gamma ds \\ &\leqslant \eta(t) \left[\frac{1}{\eta(t)} \int_{t_1}^t \left[-k_1'(s) \right]^{(p-1+\delta_0)} \left[-k_1'(s) \right]^{1-\delta_0} \int_{\Gamma_1} |u(t) - u(t-s)|^2 d\Gamma ds \right]^{\frac{\delta_0}{p-1+\delta_0}} \\ &\leqslant \left[\int_{t_1}^t \left[-k_1'(s) \right]^p \int_{\Gamma_1} |u(t) - u(t-s)|^2 d\Gamma ds \right]^{\frac{\delta_0}{p-1+\delta_0}} \\ &\leqslant c \left[\int_{t_1}^t k_1''(s) \int_{\Gamma_1} |u(t) - u(t-s)|^2 d\Gamma ds \right]^{\frac{\delta_0}{p-1+\delta_0}} \leqslant c \left[-E'(t) \right]^{\frac{\delta_0}{p-1+\delta_0}}. \end{split}$$

Similarly

$$-\int_{t_1}^t k_2'(s) \int_{\Gamma_1} \left| \frac{\partial u(t)}{\partial \nu} - \frac{\partial u(t-s)}{\partial \nu} \right|^2 d\Gamma \, ds \leqslant c \big[-E'(t) \big]^{\frac{\delta_0}{p-1+\delta_0}}.$$

Then, particularly for $\delta_0 = \frac{1}{2}$, we find that (3.14) becomes

$$F'(t) \leq -m\theta E(t) + c\theta \left[-E'(t) \right]^{\frac{1}{2p-1}} + c\theta^{\frac{p-1}{p}} \left[-E'(t) \right]^{\frac{1}{p}}.$$

Now, we multiply by $E^{2p-2}(t)$ to get, using (3.1),

$$\left(FE^{2p-2}\right)' \leqslant F'(t)E^{2p-2} \leqslant -m\theta E^{2p-1} + c\theta E^{2p-2} \left[-E'\right]^{\frac{1}{2p-1}} + c\theta^{\frac{p-1}{p}} E^{2p-2} \left[-E'\right]^{\frac{1}{p}}.$$

Then, Young's inequality gives

$$\left(FE^{2p-2}\right)' \leqslant -m\theta E^{2p-1}(t) + \varepsilon\theta E^{2p-1}(t) + C_{\varepsilon}\theta\left(-E'(t)\right) + \delta\theta E^{2p} + C_{\delta}\left(-E'(t)\right).$$

Consequently, as $E^{2p}(t) \leq E(0)E^{2p-1}(t)$, picking $\varepsilon + \delta E(0) < m$, we obtain

$$F_0'(t) \leqslant -m'\theta(t)E^{2p-1}(t),$$

where $F_0 = FE^{2p-2} + CE \sim E$. Hence we have, for some $a_0 > 0$,

$$F_0'(t) \leqslant -a_0\theta(t)F_0^{2p-1}(t)$$

from which we easily deduce that

$$E(t) \leq \frac{a}{(a' \int_0^t \theta(s) \, ds + a'')^{\frac{1}{2p-2}}}.$$
(3.17)

By recalling that p < 3/2 and using (3.17), we find that $\int_0^{+\infty} \theta(s) E(s) ds < +\infty$. Hence, by noting that

$$\theta(t) \int_0^t \int_{\Gamma_1} \left| u(t) - u(t-s) \right|^2 d\Gamma \, ds \leqslant c \int_0^t \theta(s) E(s) \, ds,$$

$$\theta(t) \int_0^t \int_{\Gamma_1} \left| \frac{\partial u(t)}{\partial \nu} - \frac{\partial u(t-s)}{\partial \nu} \right|^2 d\Gamma \, ds \leqslant c \int_0^t \theta(s) E(s) \, ds,$$

estimate (3.14) gives

$$\begin{split} F'(t) &\leq -m\theta E(t) + c\theta \int_{\Gamma_{1}} \left(\left[-k_{1}' \right]^{p \cdot \frac{1}{p}} \circ u \right)(t) \, d\Gamma + c\theta \int_{\Gamma_{1}} \left(\left[-k_{2}' \right]^{p \cdot \frac{1}{p}} \circ \frac{\partial u}{\partial \nu} \right)(t) \, d\Gamma \\ &+ c\theta^{\frac{p-1}{p}} \left[-E'(t) \right]^{\frac{1}{p}} \\ &\leq -m\theta E(t) + c\theta^{\frac{1}{p}} \left[\int_{\Gamma_{1}} \left(\left[-k_{1}' \right]^{p} \circ u \right)(t) \, d\Gamma \right]^{\frac{1}{p}} \\ &+ c\theta^{\frac{1}{p}} \left[\int_{\Gamma_{1}} \left(\left[-k_{2}' \right]^{p} \circ \frac{\partial u}{\partial \nu} \right)(t) \, d\Gamma \right]^{\frac{1}{p}} + c\theta^{\frac{p-1}{p}} \left[-E'(t) \right]^{\frac{1}{p}} \\ &\leq -m\theta E(t) + c\theta^{\frac{p-1}{p}} \left[\int_{\Gamma_{1}} \left(k_{1}'' \circ u \right)(t) \, d\Gamma \right]^{\frac{1}{p}} + c\theta^{\frac{p-1}{p}} \left[\int_{\Gamma_{1}} \left(k_{2}'' \circ \frac{\partial u}{\partial \nu} \right)(t) \, d\Gamma \right]^{\frac{1}{p}} \\ &+ c\theta^{\frac{p-1}{p}} \left[-E'(t) \right]^{\frac{1}{p}} \\ &\leq -m\theta E(t) + c\theta^{\frac{p-1}{p}} \left[-E'(t) \right]^{\frac{1}{p}}. \end{split}$$

Therefore, repeating the above steps, with multiplying by $E^{p-1}(t)$, we arrive at

$$E(t) \leq \frac{a}{(a'\int_0^t \theta(s)\,ds + a'')^{\frac{1}{p-1}}} = cG^{-1}\bigg(c'\int_0^t \theta(s)\,ds + c''\bigg).$$

(II) The general case: We define I(t) by

$$I(t) := \int_{t_1}^t \frac{-k_1'(s)}{H_0^{-1}(k_1''(s))} \int_{\Gamma_1} |u(t) - u(t-s)|^2 d\Gamma ds,$$

where H_0 is such that (2.8) is satisfied. As in (3.15), we find that I(t) satisfies, for all $t \ge t_1$,

$$I(t) < 1. \tag{3.18}$$

We also assume, without loss of generality that I(t) > 0, for all $t > t_1$; otherwise (3.14) yields an exponential decay. In addition, we define $\xi(t)$ by

$$\xi(t) := \int_{t_1}^t k_1''(s) \frac{-k_1'(s)}{H_0^{-1}(k_1''(s))} \int_{\Gamma_1} \left| u(t) - u(t-s) \right|^2 d\Gamma \, ds$$

and infer from (A2) and the properties of H_0 and D that

$$\frac{-k_i'(s)}{H_0^{-1}(k_i''(s))} \leqslant \frac{-k_i'(s)}{H_0^{-1}(H(-k_i'(s)))} = \frac{-k_i'(s)}{D^{-1}(-k_i'(s))} \leqslant k_0 \quad \forall i = 1, 2,$$

for some positive constant k_0 . Then, using (3.1) and choosing t_1 even larger (if needed), one can easily see that $\xi(t)$ satisfies, for all $t > t_1$,

$$\xi(t) \leq k_0 \int_{t_1}^t k_1''(s) \int_{\Gamma_1} |u(t) - u(t-s)|^2 d\Gamma ds$$

$$\leq c E(0) \int_{t_1}^t k_1''(s) \leq -ck_1'(t_1) E(0)$$

$$< \frac{1}{3} \min\{r, H(r), H_0(r)\}.$$
 (3.19)

Since H_0 is strictly convex on (0, r] and $H_0(0) = 0$, then

$$H_0(\mu x) \leq \mu H_0(x)$$

provided $0 \le \mu \le 1$ and $x \in (0, r]$. The use of this fact, hypothesis (A2), (2.10), (3.18), (3.19), and Jensen's inequality leads to

$$\xi(t) = \frac{1}{I(t)} \int_{t_1}^t I(t) H_0 \Big[H_0^{-1} \big(k_1''(s) \big) \Big] \frac{-k_1'(s)}{H_0^{-1}(k_1''(s))} \int_{\Gamma_1} \big| u(t) - u(t-s) \big|^2 \, d\Gamma \, ds$$

$$\geq \frac{1}{I(t)} \int_{t_1}^t H_0 \Big[I(t) H_0^{-1} \big(k_1''(s) \big) \Big] \frac{-k_1'(s)}{H_0^{-1}(k_1''(s))} \int_{\Gamma_1} \big| u(t) - u(t-s) \big|^2 \, d\Gamma \, ds$$

$$\geq H_0 \Big(\frac{1}{I(t)} \int_{t_1}^t I(t) H_0^{-1} \big(k_1''(s) \big) \frac{-k_1'(s)}{H_0^{-1}(k_1''(s))} \int_{\Gamma_1} \big| u(t) - u(t-s) \big|^2 \, d\Gamma \, ds \Big)$$

$$= H_0 \Big(-\int_{t_1}^t k_1'(s) \int_{\Gamma_1} \big| u(t) - u(t-s) \big|^2 \, d\Gamma \, ds \Big).$$

This implies that

$$-\int_{t_1}^t k_1'(s) \int_{\Gamma_1} |u(t) - u(t-s)|^2 d\Gamma \, ds \leqslant H_0^{-1}(\xi(t)).$$
(3.20)

We also define

$$\phi(t) := \int_{t_1}^t \frac{-k_2'(s)}{H_0^{-1}(k_2''(s))} \int_{\Gamma_1} \left| \frac{\partial u(t)}{\partial \nu} - \frac{\partial u(t-s)}{\partial \nu} \right|^2 d\Gamma \, ds,$$

$$\chi(t) := \int_{t_1}^t k_2''(s) \frac{-k_2'(s)}{H_0^{-1}(k_2''(s))} \int_{\Gamma_1} \left| \frac{\partial u(t)}{\partial \nu} - \frac{\partial u(t-s)}{\partial \nu} \right|^2 d\Gamma \, ds.$$

We similarly deduce, for all $t > t_1$, that

$$\phi(t) < 1$$

and

$$\chi(t) < \frac{1}{3} \min\{r, H(r), H_0(r)\}.$$
(3.21)

Repeating the above steps, we arrive at

$$-\int_{t_1}^t k_2'(s) \int_{\Gamma_1} \left| \frac{\partial u(t)}{\partial \nu} - \frac{\partial u(t-s)}{\partial \nu} \right|^2 d\Gamma \, ds \leqslant H_0^{-1}(\chi(t)). \tag{3.22}$$

Now we estimate the last integral in (3.14). First, we can assume that r is small enough such that

$$\operatorname{sh}(s) \leqslant \frac{1}{3} \min\{r, H(r), H_0(r)\} \quad \text{for all } |s| \leqslant r.$$
(3.23)

Then, with S(t) defined by

$$S(t) := \frac{1}{|\Omega_1|} \int_{\Omega_1} u_t h(u_t) \, dx.$$

(A3) and Jensen's inequality give

$$H^{-1}(S(t)) \ge c \int_{\Omega_1} H^{-1}(u_t h(u_t)) dx \ge c \int_{\Omega_1} h^2(u_t) dx.$$
(3.24)

Inserting the estimates (3.20), (3.22), and (3.24) into (3.14), we obtain

$$F'(t) \leqslant -m\theta(t)E(t) + c\theta(t) \Big[H_0^{-1}\big(\xi(t)\big) + H_0^{-1}\big(\chi(t)\big) + H^{-1}\big(S(t)\big) \Big], \quad \forall t \ge t_1.$$

One can easily make use of the properties of H, D, H_0 and the fact that $H_0^{-1}(S(t)) = D^{-1}(H^{-1}(S(t))), D^{-1}(0) = 0$, and $H^{-1}(S(t)) \leq r$ to deduce, for some positive constant c, that $H^{-1}(S(t)) \leq cH_0^{-1}(S(t))$. Therefore

$$F'(t) \leq -m\theta(t)E(t) + c\theta(t) \Big[H_0^{-1}(\xi(t)) + H_0^{-1}(\chi(t)) + H_0^{-1}(S(t)) \Big] \leq -m\theta(t)E(t) + c\theta(t)H_0^{-1}(\xi(t) + \chi(t) + S(t)).$$
(3.25)

Now, for $\varepsilon_0 < r$ and $c_0 > 0$, using (3.25), and the fact that $E' \leq 0$, $H'_0 > 0$, $H''_0 > 0$ on (0, r], we find that the functional F_1 , defined by

$$F_1(t) := H'_0\left(\varepsilon_0 \frac{E(t)}{E(0)}\right) F(t) + c_0 E(t)$$

satisfies, for some $\alpha_1, \alpha_2 > 0$,

$$\alpha_1 F_1(t) \leqslant E(t) \leqslant \alpha_2 F_1(t) \tag{3.26}$$

and, for all $t \ge t_1$,

$$F_{1}'(t) = \varepsilon_{0} \frac{E'(t)}{E(0)} H_{0}'' \left(\varepsilon_{0} \frac{E(t)}{E(0)} \right) F(t) + H_{0}' \left(\varepsilon_{0} \frac{E(t)}{E(0)} \right) F'(t) + c_{0} E'(t) \leq -m\theta E(t) H_{0}' \left(\varepsilon_{0} \frac{E(t)}{E(0)} \right) + c\theta H_{0}' \left(\varepsilon_{0} \frac{E(t)}{E(0)} \right) H_{0}^{-1} \left(\xi(t) + \chi(t) + S(t) \right) + c_{0} E'(t).$$
(3.27)

Let H_0^* be the convex conjugate of H_0 in the sense of Young (see [6] pp. 61–64), then

$$H_0^*(s) = s \left(H_0' \right)^{-1}(s) - H_0 \left[\left(H_0' \right)^{-1}(s) \right], \quad \text{if } s \in \left(0, H_0'(r) \right]$$
(3.28)

and H_0^* satisfies the following Young's inequality

$$AB \leq H_0^*(A) + H_0(B), \quad \text{if } A \in (0, H_0'(r)], B \in (0, r].$$
 (3.29)

With $A = H'_0(\varepsilon_0 \frac{E(t)}{E(0)})$ and $B = H_0^{-1}(\xi(t) + \chi(t) + S(t))$, using (3.1), (3.19), (3.21), (3.23), and (3.27)-(3.29), we arrive at

$$\begin{split} F_1'(t) &\leqslant -m\theta(t)E(t)H_0'\bigg(\varepsilon_0\frac{E(t)}{E(0)}\bigg) + c\theta(t)H_1^*\bigg(H_0'\bigg(\varepsilon_0\frac{E(t)}{E(0)}\bigg)\bigg) \\ &+ c\theta(t)\big(\xi(t) + \chi(t) + S(t)\big) + c_0E'(t) \\ &\leqslant -m\theta(t)E(t)H_0'\bigg(\varepsilon_0\frac{E(t)}{E(0)}\bigg) + c\varepsilon_0\theta(t)\frac{E(t)}{E(0)}H_0'\bigg(\varepsilon_0\frac{E(t)}{E(0)}\bigg) - cE'(t) + c_0E'(t). \end{split}$$

Consequently, with a suitable choice of ε_0 and c_0 , we obtain, for all $t > t_1$,

$$F_1'(t) \leqslant -\tau\theta(t) \left(\frac{E(t)}{E(0)}\right) H_0'\left(\varepsilon_0 \frac{E(t)}{E(0)}\right) = -\tau\theta(t) H_2\left(\frac{E(t)}{E(0)}\right),\tag{3.30}$$

where $H_2(t) = t H'_0(\varepsilon_0 t)$.

Since $H'_2(t) = H'_0(\varepsilon_0 t) + \varepsilon_0 t H''_0(\varepsilon_0 t)$, then, using the strict convexity of H_0 on (0, r], we find that $H'_2(t), H_2(t) > 0$ on (0, 1]. Thus, with

$$R(t) = \frac{\alpha_1 F_1(t)}{E(0)},$$

taking in account (3.26) and (3.30), we have

$$R(t) \sim E(t) \tag{3.31}$$

and, for some $c_1 > 0$,

$$R'(t) \leqslant -c_1\theta(t)H_2(R(t)), \quad \forall t > t_1.$$

Considering $H_1(t) = \int_t^1 \frac{1}{H_2(s)} ds$, we deduce that $(H_1(R))'(t) > 0$, $\forall t \ge t_1$, which implies that $H_1(R(t)), t \ge t_1$, is increasing. Thus,

$$k_1 \int_{t_1}^t \theta(s) \, ds \leqslant \int_{t_1}^t (H_1(R))'(s) \, ds \leqslant H_1(R(t)) - H_1(R(t_1)),$$

and so, for some $c_2 > 0$,

$$R(t) \leqslant H_1^{-1}\left(c_1 \int_{t_1}^t \theta(s) \, ds + c_2\right), \quad \forall t \ge t_1.$$
(3.32)

Here, we used, based on the properties of H_2 , the fact that H_1 is strictly decreasing on (0, 1]. Using (3.31)–(3.32) and by virtue of continuity and boundedness of E and θ , we obtain (2.7).

Moreover, if $\int_0^1 H_1(t) dt < +\infty$, then $\int_0^{+\infty} H_1^{-1}(t) dt < +\infty$, and so, by (2.7), $\int_0^{+\infty} E(t) dt < +\infty$. Then, we have

$$\int_0^t \int_{\Gamma_1} |u(t) - u(t-s)|^2 d\Gamma \, ds \leq c \int_0^t E(s) \, ds < +\infty,$$
$$\int_0^t \int_{\Gamma_1} \left| \frac{\partial u(t)}{\partial \nu} - \frac{\partial u(t-s)}{\partial \nu} \right|^2 d\Gamma \, ds \leq c \int_0^t E(s) \, ds < +\infty.$$

Therefore, we can repeat the same procedures with

$$I(t) := \int_{t_1}^t \int_{\Gamma_1} |u(t) - u(t-s)|^2 d\Gamma ds,$$

$$\phi(t) := \int_{t_1}^t \int_{\Gamma_1} \left| \frac{\partial u(t)}{\partial \nu} - \frac{\partial u(t-s)}{\partial \nu} \right|^2 d\Gamma ds$$

and

$$\xi(t) := \int_{t_1}^t k_1''(s) \int_{\Gamma_1} \left| u(t) - u(t-s) \right|^2 d\Gamma \, ds,$$

$$\chi(t) := \int_{t_1}^t k_2''(s) \int_{\Gamma_1} \left| \frac{\partial u(t)}{\partial \nu} - \frac{\partial u(t-s)}{\partial \nu} \right|^2 d\Gamma \, ds$$

to establish (2.9).

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